Infinitary proof theory of first order linear logic with fixed points

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	Productivity, Equality of streams; A property holds infinitely often
Induction	Coinduction - Bisimulation

Finite data types	Infinite data types
Natural numbers, Lists, etc.	Streams, Infinite trees, etc.
Termination, Progress; A property eventually holds	Productivity, Equality of streams; A property holds infinitely often
Induction	Coinduction - Bisimulation

Least fixed points	Greatest fixed points
Finite data types	Infinite data types
Natural numbers, Lists, etc.	Streams, Infinite trees, etc.
Termination, Progress; A property eventually holds	Productivity, Equality of streams; A property holds infinitely often
Induction	Coinduction - Bisimulation

Mutual least and greatest fixed points

- 1. Examples?
- 2. Induction/Coinduction?
- 3. Termination/productivity?

Prove theorems using induction and coinduction - Previous works

- Induction principle
- Bisimulation
- Coinduction principle [Kozen and Silva]
- An infinitary calculus for first-order logic with inductive definitions
 [Brotherston]
- A finitary calculus for least and greatest fixed points in linear logic [Baelde]
- Well founded recursion with copatterns and sized types [Abel and Pientka]

Our contribution

A first order calculus for proving properties about mutual least and greatest fixed points, in particular Session-typed processes

- 1. Add fixed points and assign priorities to them,
- 2. Use circular edges in the proof for inductive and coinductive steps,
- 3. Impose a validity condition to ensure soundness of this proof system.

We use priorities in the validity condition to ensure valid simultaneous induction and conduction.

Finite lists: Example of least fixed points

Natural numbers

$$\mathtt{nat} = _{\mu}^{1} \oplus \{ \mathsf{zero} : \mathsf{1}, \mathsf{succ} : \mathtt{nat} \}$$

 $\overline{3} = \text{succ succ succ zero}$

Lists of natural numbers

$$list_{nat} = {}^{1}_{\mu} \oplus \{nil : 1, cons : nat \otimes list_{nat}\}$$

$$\overline{[3,3]}=\cos(\overline{3},\cos(\overline{3},\operatorname{nil}))$$

Programming with finite lists

Append two lists

Terminating

```
l \leftarrow \operatorname{Append} \leftarrow l_1, l_2 = \\ \operatorname{\mathbf{case}} l_1 \ (\mu_{list} \Rightarrow \\  \\ \operatorname{\mathbf{case}} l_1 \ (nil): \text{ forward I2 to I.} \\ \\ \operatorname{\mathbf{case}} l_1 \ (nil \Rightarrow \operatorname{\mathbf{wait}} l_1; l \leftarrow l_2 \\ \\ \operatorname{\mathbf{send}} x \text{ to I and call Append} \\ \text{on I2 and the remaining of I1.} \\ \\ \\ \operatorname{\mathbf{case}} l_1 \ (nil \Rightarrow \operatorname{\mathbf{wait}} l_1; l \leftarrow l_2 \\ \\ \operatorname{\mathbf{cons}} \Rightarrow l.\mu_{list}; \\ \\ x \leftarrow \operatorname{\mathbf{recv}} l; \\ \\ l.cons; \operatorname{\mathbf{send}} l \ x; l \leftarrow \operatorname{\mathbf{Append}} \leftarrow l_1 \ l_2)) \\ \\
```

I use linear binary session typed processes for programming examples. See [1,2] for more info.

Termination and List as first order predicates

$$List(l_1) \vdash Terminate(_ \leftarrow Append \leftarrow l_1 _)$$

$$\begin{split} \textit{Terminate}(_ \leftarrow \mathsf{Append} \leftarrow \mathsf{nil}_) &=^1_{\mu} 1 \\ \textit{Terminate}(_ \leftarrow \mathsf{Append} \leftarrow (\mathsf{cons}(x) :: l_1')_) &=^1_{\mu} \textit{Terminate}(_ \leftarrow \mathsf{Append} \leftarrow l_1'_) \end{split}$$

```
List(nil) = {}^1_{\mu} 1

List(cons(x) :: l'_1) = {}^1_{\mu} List(l'_1)
```

Append terminates - proof

 $List(l_1) \vdash Terminate(_ \leftarrow Append \leftarrow l_1 _)$

$$\frac{\frac{\vdots \vdash 1}{1 \vdash 1} \ 1L}{1 \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow \mathsf{nil}_)} \ \mu R$$

$$\frac{1 \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow \mathsf{nil}_)}{\dagger \ List(\mathsf{nil}) \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow \mathsf{nil}_)} \ \mu L$$

$$\frac{List(l_1') \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow l_1'_)}{List(l_1') \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow (\mathsf{cons}(x) :: l_1')_)} \ \mu R$$

$$\frac{List(\mathsf{cons}(x) :: l_1') \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow (\mathsf{cons}(x) :: l_1')_)}{\dagger \ List(\mathsf{cons}(x) :: l_1') \vdash Terminate(_ \leftarrow \mathsf{Append} \leftarrow (\mathsf{cons}(x) :: l_1')_)} \ \mu L$$

merge split₁ split₂

Merge two streams into a single stream by alternatively outputting an element of each.

Return the odd elements of a stream.

Return the even elements of a stream.

$$merge(split_1(t), split_2(t)) = t$$

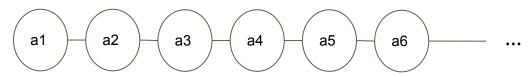
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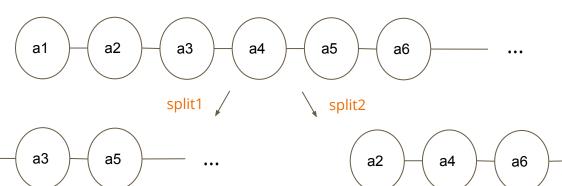
a1

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merge split₁ split₂

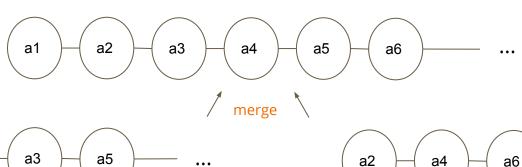
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Merge two streams into a single stream by alternatively outputting an element of each.

Return the odd elements of a stream.

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$merge(split_1(t), split_2(t)) = t$



Programming with streams

Define properties of merge and splits as:

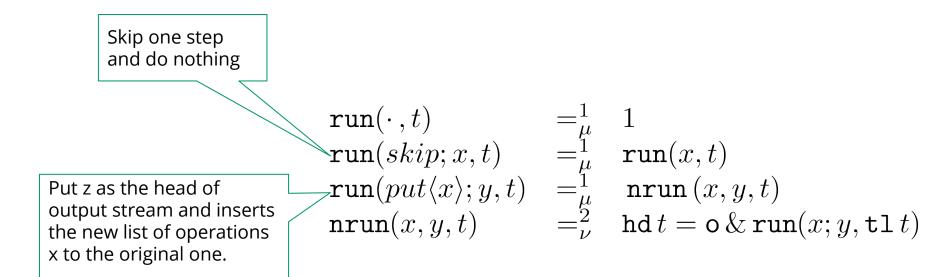
$$\begin{array}{lll} \mathtt{Merge}(x,y,z) &=^1_{\nu} & (\mathsf{hd}\,z = \mathsf{hd}\,x\,\&\, \mathsf{Merge}\,(y,\mathsf{tl}\,x,\mathsf{tl}\,z)) \\ \mathtt{Split}_1(x,y) &=^1_{\nu} & (\mathsf{hd}\,y = \mathsf{hd}\,x\,\&\, \mathtt{Split}_2(\mathsf{tl}\,x,\mathsf{tl}\,y)) \\ \mathtt{Split}_2(x,y) &=^1_{\nu} & (1\,\&\, \mathtt{Split}_1(\mathsf{tl}\,x,y)) \end{array}$$

Operations merge and split are inverses

```
\frac{\frac{- \vdash \operatorname{hd} y_1 = \operatorname{hd} y_1}{\operatorname{hd} y_1 = \operatorname{hd} x \vdash \operatorname{hd} x = \operatorname{hd} y_1}{\operatorname{hd} y_1 = \operatorname{hd} x \vdash \operatorname{hd} x = \operatorname{hd} y_1} = L}{\frac{\operatorname{hd} y_1 = \operatorname{hd} x , 1 \vdash \operatorname{hd} x = \operatorname{hd} y_1}{\operatorname{hd} y_1 = \operatorname{hd} x , 1 \vdash \operatorname{hd} x = \operatorname{hd} y_1} }{\operatorname{hd} y_1 = \operatorname{hd} x , 1 \& \operatorname{S}_1(\operatorname{tl} x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1} } \underbrace{ \underbrace{ \begin{array}{c} \operatorname{S}_2(x, y_2), \operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x) \\ \operatorname{S}_2(\operatorname{tl} x, \operatorname{tl} y_1), \operatorname{S}_1(\operatorname{tl} x, y_2) \vdash \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{S}_2(\operatorname{tl} x, \operatorname{tl} y_1), 1 \& \operatorname{S}_1(\operatorname{tl} x, y_2) \vdash \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{hd} y_1 = \operatorname{hd} x \& \operatorname{S}_2(\operatorname{tl} x, \operatorname{tl} y_1), 1 \& \operatorname{S}_1(\operatorname{tl} x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1 \& \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{hd} y_1 = \operatorname{hd} x \& \operatorname{S}_2(\operatorname{tl} x, \operatorname{tl} y_1), 1 \& \operatorname{S}_1(\operatorname{tl} x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1 \& \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{hd} y_1 = \operatorname{hd} x \& \operatorname{S}_2(\operatorname{tl} x, \operatorname{tl} y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1 \& \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{S}_1(x, y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1 \& \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{S}_1(x, y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{Hd}(y_1, y_2, x) \\ \leftarrow \underbrace{\operatorname{S}_1(x, y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{hd} x = \operatorname{hd} y_1 \& \operatorname{M}(y_2, \operatorname{tl} y_1, \operatorname{tl} x) \\ \operatorname{S}_1(x, y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{Hd}(y_1, y_2, x) \\ \leftarrow \underbrace{\operatorname{S}_1(x, y_1), \operatorname{S}_2(x, y_2) \vdash \operatorname{Hd}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} } \underbrace{\operatorname{S}_1(x, y_1) \vdash \operatorname{M}(y_1, y_2, x)} \underbrace{\operatorname{S}_1(x, y_
```

Programming with mutual least and greatest fixed points

run(x,t): A stream producer where x is the list of operations, and t is the output stream.



Run on any list of operations produces a (possibly infinite) list of elements "o"

```
\begin{array}{lll} \operatorname{run}(\cdot\,,t) & =_{\mu}^{1} & 1 \\ \operatorname{run}(skip;x,t) & =_{\mu}^{1} & \operatorname{run}(x,t) \\ \operatorname{run}(put\langle x\rangle;y,t) & =_{\mu}^{1} & \operatorname{nrun}(x,y,t) \\ \operatorname{nrun}(x,y,t) & =_{\nu}^{2} & \operatorname{hd}t = \operatorname{o}\&\operatorname{run}(x;y,\operatorname{tl}t) \end{array}
                \begin{array}{ll} \mathtt{list_o}(t) &=^1_{\mu} & \oplus \{\mathtt{nil}: 1, \mathtt{next}: \mathtt{stream_o}(t)\} \\ \mathtt{stream_o}(t) &=^2_{\nu} & \& \{\mathtt{hd}: \mathtt{hd}\, t = \mathtt{o}, \mathtt{tl}: \mathtt{list_o}\, (\mathtt{tl}\, t)\} \end{array}
               (\dagger) \operatorname{run}(x,t) \vdash \operatorname{list}_{o}(t)
(\star) \operatorname{nrun}(x, y, t) \vdash \operatorname{stream}_{o}(t)
```

Run produces a listo - proof

```
\begin{array}{lll} \operatorname{run}(\cdot\,,t) & = \frac{1}{\mu} & 1 \\ \operatorname{run}(skip;x,t) & = \frac{1}{\mu} & \operatorname{run}(x,t) \\ \operatorname{run}(put\langle x\rangle;y,t) & = \frac{1}{\mu} & \operatorname{nrun}(x,y,t) \\ \operatorname{nrun}(x,y,t) & = \frac{2}{\nu} & \operatorname{hd}t = \operatorname{o}\&\operatorname{run}(x,t) \end{array}
                                                                                                                                        hdt = o \& run(x; y, tlt)
```

```
 \begin{array}{c} \frac{\overline{\cdot \vdash 1} \ 1R}{ \cdot \vdash \oplus \{\mathsf{nil} : 1, \mathsf{next} : \mathsf{stream}_{\mathsf{o}}(t)\}} \ \oplus R \\ \\ \frac{\frac{\cdot \vdash \mathsf{list}_{\mathsf{o}}(t)}{1 \vdash \mathsf{list}_{\mathsf{o}}(t)} \ 1L}{1 \vdash \mathsf{list}_{\mathsf{o}}(t)} \ \mu_{\mathsf{run}} L \\ \hline \\ \frac{\mathsf{run}(x, t) \vdash \mathsf{list}_{\mathsf{o}}(t)}{\dagger \, \mathsf{run}((skip; x), t) \vdash \mathsf{list}_{\mathsf{o}}(t)} \ \mu_{\mathsf{run}} L \end{array} 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              \frac{ \frac{\operatorname{nrun}(x,y,t) \vdash \operatorname{stream}_{\mathsf{o}}(t)}{\operatorname{nrun}(x,y,t) \vdash \oplus \{\operatorname{nil}: 1, \operatorname{next}: \operatorname{stream}_{\mathsf{o}}(t)\}}{\frac{\operatorname{nrun}(x,y,t) \vdash \operatorname{list}_{\mathsf{o}}(t)}{\dagger \operatorname{run}(put\langle x\rangle; y, t) \vdash \operatorname{list}_{\mathsf{o}}(t)}} \overset{\oplus R}{\mu_{\operatorname{list}_{\mathsf{o}}} R}
\frac{\frac{\overline{\operatorname{hd}\,t} = \operatorname{o} \vdash \operatorname{hd}\,t = \operatorname{o}}{\operatorname{\mathbb{E}} \operatorname{hd}\,t = \operatorname{o}}}{\operatorname{\mathbb{E}} \operatorname{ID}} \underbrace{\frac{\operatorname{\mathbb{E}} \operatorname{\mathbb{E}} \operatorname{\mathbb{E}}
```

 $\overline{\operatorname{nrun}\left(x,y,t\right) \vdash \&\{\operatorname{hd}:\operatorname{hd}t=\operatorname{o},\operatorname{tl}:\operatorname{list_o}(\operatorname{tl}t)\}} \ \nu_{\operatorname{stream_o}}R$

 $\star \operatorname{nrun}(x, y, t) \vdash \operatorname{stream}_{o}(t)$

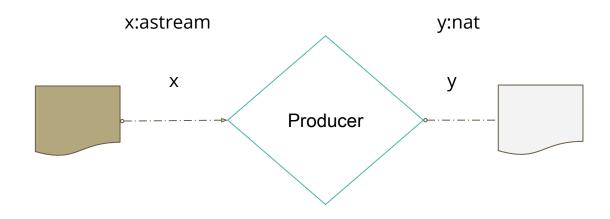
Strong progress and Validity condition

A process satisfies *strong progress*, if after *finite number of steps*, it either becomes *empty* or attempts to *communicate to the left or right* [2].

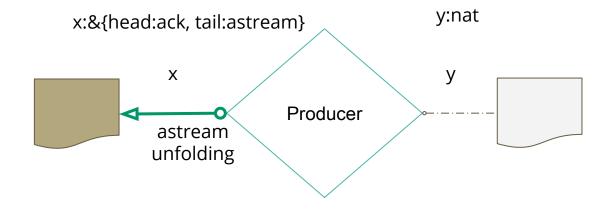
Theorem. Our *validity condition* on session-typed processes ensures *strong progress* [2].

We want to prove this directly using our calculus.

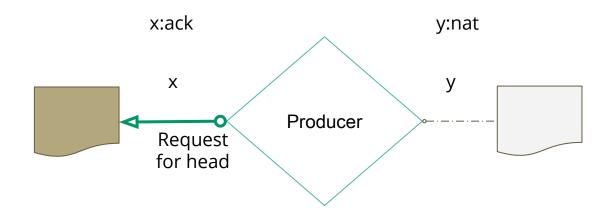
```
\Sigma := \mathsf{ack} =_{\mu}^{1} \oplus \{ack : \mathsf{astream}\}, \qquad \qquad z : \mathsf{ack} \vdash w \leftarrow \mathsf{Idle} \leftarrow z :: (w : \mathsf{nat}) \\ \mathsf{astream} =_{\nu}^{2} \& \{head : \mathsf{ack}, \ tail : \mathsf{astream}\}, \qquad x : \mathsf{astream} \vdash y \leftarrow \mathsf{Producer} \leftarrow x :: (y : \mathsf{nat}), \\ \mathsf{nat} =_{\mu}^{3} \oplus \{z : 1, \ s : nat\}
```



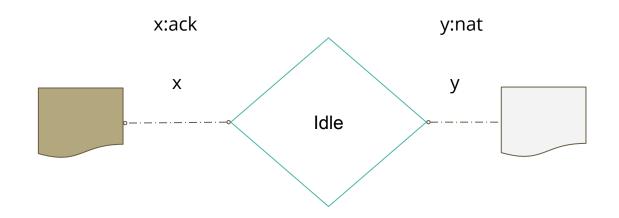
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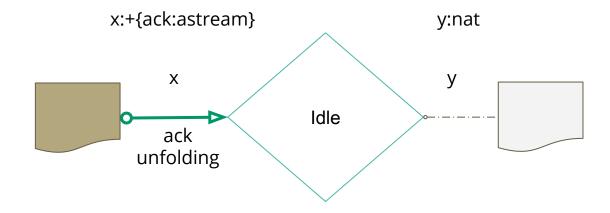
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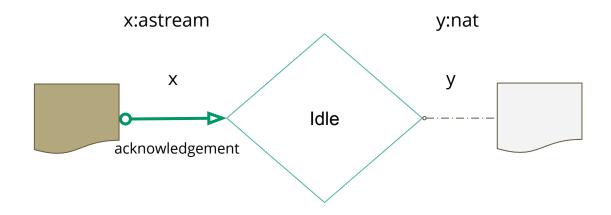
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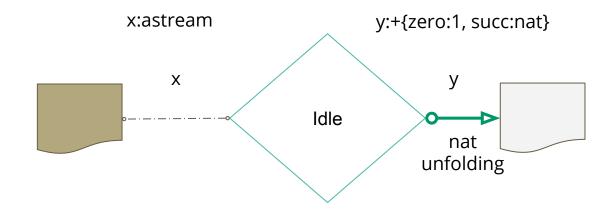
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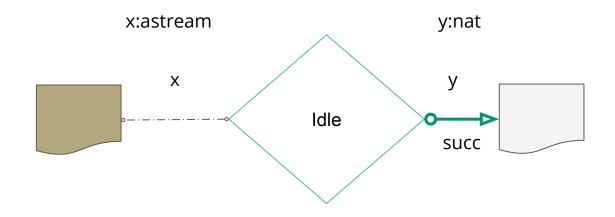
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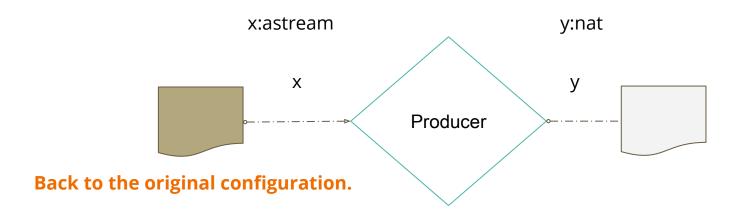
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```



$$\Sigma := \operatorname{ack} =^1_{\mu} \oplus \{ack : \operatorname{astream}\},$$

$$\operatorname{astream} =^2_{\nu} \& \{head : \operatorname{ack}, \quad tail : \operatorname{astream}\},$$

$$\operatorname{nat} =^3_{\mu} \oplus \{z : 1, \quad s : nat\}$$

 $z : ack \vdash w \leftarrow Idle \leftarrow z :: (w : nat)$ $x : astream \vdash y \leftarrow Producer \leftarrow x :: (y : nat),$

$$y^{0} \leftarrow \text{Producer} \leftarrow x^{0} =$$
 $Lx^{0}.\nu_{astream};$
 $Lx^{1}.head; y^{0} \leftarrow \text{Idle} \leftarrow x^{1}$

Eventually communicate with its external channels

$$y^{0} \leftarrow \text{Idle} \leftarrow x^{1} =$$
 $\operatorname{\mathbf{case}} Lx^{1} (\mu_{ack} \Rightarrow$
 $\operatorname{\mathbf{case}} Lx^{2} (ack \Rightarrow Ry^{0}.\mu_{nat};$
 $Ry^{1}.s; y^{1} \leftarrow \text{Producer} \leftarrow x^{2}))$

This example is adapted from [2].

$$\Sigma := \mathsf{ack} =^1_\mu \oplus \{ack : \mathsf{astream}\}, \qquad \qquad x : \mathsf{nat} \vdash \mathsf{D}$$

$$\mathsf{astream} =^2_\nu \& \{head : \mathsf{ack}, \quad tail : \mathsf{astream}\}, \qquad \qquad w : \mathsf{astream}$$

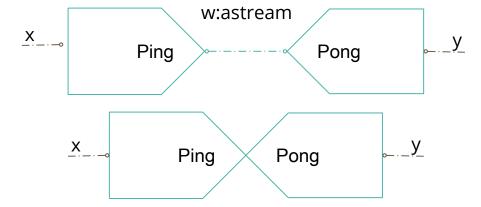
$$\mathsf{nat} =^3_\mu \oplus \{z : 1, \quad s : nat\}$$

$$\qquad x : \mathsf{nat} \vdash \mathsf{D}$$

$$x : \mathsf{nat} \vdash \mathsf{Ping} :: (w : \mathsf{astream})$$
 $w : \mathsf{astream} \vdash \mathsf{Pong} :: (y : \mathsf{nat})$
 $x : \mathsf{nat} \vdash \mathsf{PingPong} :: (y : \mathsf{nat})$

$$\begin{split} \Sigma := & \ \text{ack} =_{\mu}^1 \oplus \{ack : \text{astream}\}, \\ & \ \text{astream} =_{\nu}^2 \& \{head : \text{ack}, \quad tail : \text{astream}\}, \\ & \ \text{nat} =_{\mu}^3 \oplus \{z : 1, \quad s : nat\} \end{split}$$

 $x : \mathtt{nat} \vdash \mathtt{Ping} :: (w : \mathtt{astream})$ $w : \mathtt{astream} \vdash \mathtt{Pong} :: (y : \mathtt{nat})$ $x : \mathtt{nat} \vdash \mathtt{PingPong} :: (y : \mathtt{nat})$

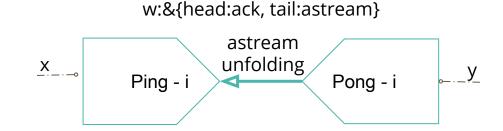


$$\Sigma := \mathsf{ack} =_{\mu}^{1} \oplus \{ack : \mathsf{astream}\}, \qquad \qquad x : \mathsf{nat} \vdash \mathsf{Ping} :: (w : \mathsf{astream})$$

$$\mathsf{astream} =_{\nu}^{2} \& \{head : \mathsf{ack}, \quad tail : \mathsf{astream}\}, \qquad w : \mathsf{astream} \vdash \mathsf{Pong} :: (y : \mathsf{nat})$$

$$\mathsf{nat} =_{\mu}^{3} \oplus \{z : 1, \quad s : nat\}$$

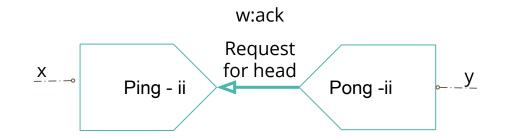
$$x : \mathsf{nat} \vdash \mathsf{PingPong} :: (y : \mathsf{nat})$$



$$\Sigma := \mathsf{ack} =^1_\mu \oplus \{ack : \mathsf{astream}\}, \qquad \qquad x : \mathsf{nat} \vdash \mathsf{Ping} :: (w : \mathsf{astream})$$

$$\mathsf{astream} =^2_\nu \& \{head : \mathsf{ack}, \quad tail : \mathsf{astream}\}, \qquad \qquad w : \mathsf{astream} \vdash \mathsf{Pong} :: (y : \mathsf{nat})$$

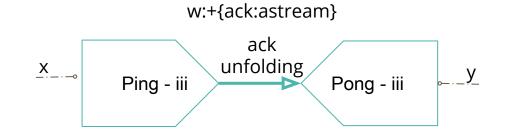
$$\mathsf{nat} =^3_\mu \oplus \{z : 1, \quad s : nat\} \qquad \qquad x : \mathsf{nat} \vdash \mathsf{PingPong} :: (y : \mathsf{nat})$$



$$\Sigma := \mathsf{ack} =^1_\mu \oplus \{ack : \mathsf{astream}\}, \qquad \qquad x : \mathsf{nat} \vdash \mathsf{Ping} :: (w : \mathsf{astream})$$

$$\mathsf{astream} =^2_\nu \& \{head : \mathsf{ack}, \quad tail : \mathsf{astream}\}, \qquad \qquad w : \mathsf{astream} \vdash \mathsf{Pong} :: (y : \mathsf{nat})$$

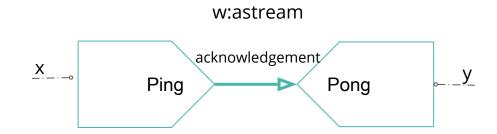
$$\mathsf{nat} =^3_\mu \oplus \{z : 1, \quad s : nat\} \qquad \qquad x : \mathsf{nat} \vdash \mathsf{PingPong} :: (y : \mathsf{nat})$$



$$\Sigma := \mathsf{ack} =^1_\mu \oplus \{ack : \mathsf{astream}\}, \qquad \qquad x : \mathsf{nat} \vdash \mathsf{Ping} :: (w : \mathsf{astream})$$

$$\mathsf{astream} =^2_\nu \& \{head : \mathsf{ack}, \quad tail : \mathsf{astream}\}, \qquad \qquad w : \mathsf{astream} \vdash \mathsf{Pong} :: (y : \mathsf{nat})$$

$$\mathsf{nat} =^3_\mu \oplus \{z : 1, \quad s : nat\} \qquad \qquad x : \mathsf{nat} \vdash \mathsf{PingPong} :: (y : \mathsf{nat})$$



Back to the original configuration.

Ping-Pong: an invalid program - code

```
\begin{aligned} y &\leftarrow \texttt{PingPong} \leftarrow x = \\ w &\leftarrow \texttt{Ping} \leftarrow x; & \% \ spawn \ process \ \texttt{Ping}_w \\ y &\leftarrow \texttt{Pong} \leftarrow w & \% \ \textit{continue with a tail call} \end{aligned}
```

Keep calling itself without communicating with its external channels

```
[0,0,0,0,0,0]
w \leftarrow \texttt{Ping} \leftarrow x =
         \operatorname{case} Rw \ (\nu_{astream} \Rightarrow
                                                                                               [0,0,-1,0,0,0]
                        case Rw \ (head \Rightarrow Rw.\mu_{ack};
                                                                                               [0, 1, -1, 0, 0, 0]
                                                 Rw.ack; w \leftarrow \texttt{Ping} \leftarrow x [0, 1, -1, 0, 0, 0]
                                      | tail \Rightarrow w \leftarrow \texttt{Ping} \leftarrow x))
                                                                                               [0,0,-1,0,0,0]
                                                                              [0,0,0,0,0,0]
  y \leftarrow \texttt{Pong} \leftarrow w =
          Lw.\nu_{astream};
                                                                              [0,0,0,1,0,0]
            Lw.head;
                                                                              [0,0,0,1,0,0]
              \mathbf{case}\,Lw\ (\mu_{ack} \Rightarrow
                                                                              [-1, 0, 0, 1, 0, 0]
                   \mathbf{case}\,Lw (
                                                                              [-1, 0, 0, 1, 0, 0]
                                                                             [-1, 0, 0, 1, 0, 1]
                                 ack \Rightarrow Ry.\mu_{nat};
                                      Ry.s;
                                                           [-1,0,0,1,0,1]
                                          y \leftarrow \text{Pong} \leftarrow w) [-1,0,0,1,0,1]
```

A valid configuration of processes satisfies strong progress

We define strong progress as a predicate

$$\mathcal{C} \in [\![x:A]\!]$$

$$\cdot \vdash \mathcal{C} :: (x:A) \subset \mathbb{B}$$

Theorem. If configuration C is well-typed then there is an infinite derivation for its strong progress property. Moreover, if it C is valid, the infinite derivation is a proof.

Conclusion

We introduced an infinitary sequent calculus for first order intuitionistic multiplicative additive linear logic with fixed points [2].

Our main motivation for introducing this calculus is to reason about programs behaviour. In particular we use this calculus to give a direct proof for the strong progress property of locally valid binary session typed processes [2]. The importance of a direct proof other than its elegance is that it can be adapted for a more general validity condition on processes without the need to prove cut elimination productivity for their underlying derivations.

Send me an Email!

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